SUNSTAR传感与控制 http://www.sensor-ic.com/ TEL:0755-83376549 FAX:0755-83376182 E-MA9LP:金金2006 ED-19 Quadrature Output Series Magnetic Encoder

The ED-19 Series Magnetic Encoder is

designed for medium duty feedback applications. Resolutions are available from 64 to 256 counts per revolution. The magnetic technology used in the ED19 series is plug-in compatible with existing encoder products, with the wadded advantages of an extended temperature range and fully sealed electronics. The ED19 suffers no LED degradation, as with conventional optical encoders, meaning it has a virtually unlimited life.

FEATURES

- Magnetic Sensing Technology •
- **Encapsulated Electronics/Sealed Unit** •
- Harsh Environment Compatibility
- Quadrature Outputs •
- Low Profile •
- **Consistent Rotational Torque** •
- Resistant to Contamination •
- **IP52 Sealing** •
- Metallic Threaded Bushing Mounting •
- Wide Operational Temperature Range • (-40 °C to 85 °C)
- Custom Housings, Shafts, Connectors • Available in Most Cases with No Additional **Tooling Required**
- **Sleeve Bearing**
- Excellent Stability No Optical Degradation

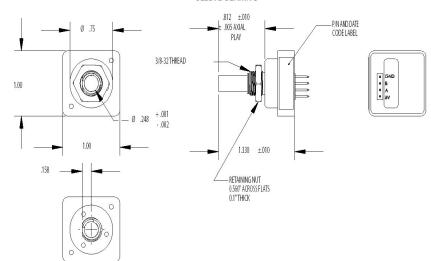
APPLICATIONS

- Marine, Avionics, Motor Speed and Position • Control
- Marine Steering and Throttle Position Control/Feedback
- Monitor Pump Speed and Direction •
- **Camera Position and Control** •
- XY Stage Positioning
- Radio Controls •
- Medical Diagnostic Equipment •
- Video and Sound Editing Equipment .
- Valve Position .
- Syringe Pump •

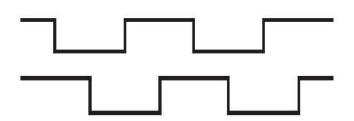
1000 Lucas Way Hampton, VA 23666

Motor Feedback •





sample quadrature output



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08/19/2008



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Measurement Specialties reserves the right to update and change these specifications without notice.

300 RPM

Sleeve

3,000,000 cycles

PERFORMANCE SPECIFICATIONS

Standard Resolution Operating Temperature

Maximum Speed Bearing Life Bearings Run Out Bushing Mounting Torque

ELECTRICAL

Maximum Current Draw15 mAOperating Voltage (VDC) 5 ± -0.25 VDCOutput TypeOpen Collector with internal 10 k Ω pullupVoltage Output High (Voh)Minimum 4.75 VdcVoltage Output Low (Vol)Maximum 125mV @ 16 mADuty Cycle $50\% \pm -25\%$ Phase Angle $90^{\circ} \pm -45^{\circ}$ (Ch. A leads Ch. B Clockwise)Note: All specifications are specified with Vdd @ 5.00 Vdc and Ambient Temperature Ta @ 25 Degrees Celsius.

10 in-lb max

MECHANICAL

Axial Load (lbs) Radial Load (lbs) Operating Speed (rpm) Shaft End Play (in) Shaft Radial Play (in) Shaft Push-in Force (lbs) Shaft Pull-out Force (lbs)

ENVIRONMENTAL

Vibration

Shock

Humidity

Thermal Shock

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Operating Temperature Storage Temperature

4.5 [20 N] Max. 2.25 [10 N] Max. 300 = Sleeve .005 [.10] Max. .010 [.25] Max. @ .6 [15.2] from mounting surface 40 [9N] 6 [1.3N]

256, 128 and 64 counts per revolution (CPR) 4 counts=1 pulse

-40 °C to +85 °C (Extended temperature

.010" max @ .75" from mounting surface

range available, contact factory for details)

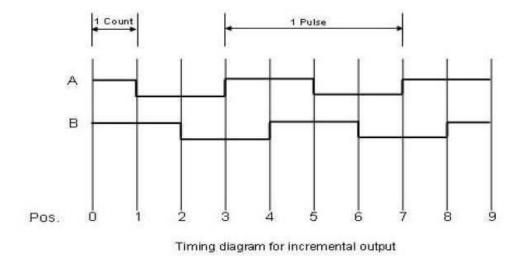
MIL-STD-202F Method 204D Test Condition B
MIL-STD-202F Method 213B Test Condition C
MIL-STD-202F Method 103B Test Condition A
MIL-STD-202F Method 107G Test Condition A
-40 to +85 ℃
-55 to 125 ℃

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measureme

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Quadrature timing

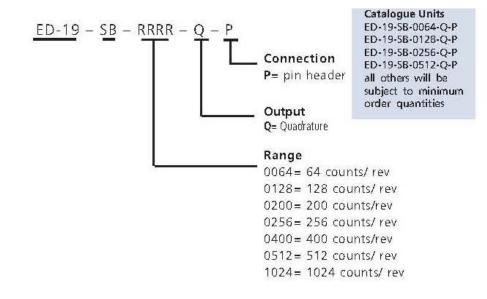


Channel A leads when Channel B shaft is rotated in Clockwise direction.

measurement

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