

The ED-21 Series Magnetic

Encoder is designed to replace traditional mechanical potentiometers. This product is offered with a ball bearing supported shaft. 5 standard output ranges are available: 0.5 - 4.5v, 0 - 5v, 0 - 12v, 4 - 20mA and 0 - 20mA. The magnetic technology used in the ED-21 offers advantages over conventional electomechanical potentiometers with sealed electronics, extended temperature ranges, and virtually unlimited life as there are no mechanical parts to wear out.



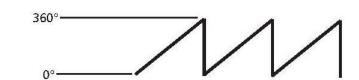
dimensions

0.497 ± 0.010

FEATURES

- Magnetic Sensing Technology
- Encapsulated Electronics/Sealed Unit
- Harsh Environment Compatibility
- Analog Voltage and Current Outputs
- Low Profile
- Consistent Rotational Torque
- Resistant to Contamination •
- IP52 Sealing
- Metallic Threaded Bushing Mounting
- Wide Operational Temperature Range (-40 ℃ to 85 °C)
- Custom Housings, Shafts, Connectors Available in Most Cases with No Additional **Tooling Required**
- **Excellent Stability**

sample analog output



APPLICATIONS

- Marine, Avionics, Motor Speed and Position Control
- Marine Steering and Throttle Position Control/Feedback
- Monitor Pump Speed and Direction
- Camera Position and Control
- XY Stage Positioning
- Radio Controls
- Motor Feedback
- Medical Diagnostic Equipment
- Video and Sound Editing Equipment
- Valve Position
- Syringe Pump
- Potentiometer Replacement

ED-21 Rev 1

www.meas-spec.com

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Performance Specifications

Standard Outputs ranges over 360° .5 – 4.5 vdc, 4-20 mA, 0-5 Vdc, 0-12 VDC, 0-20 mA

Operating Temperature -40C to +85 ℃

Maximum Speed Up to 3000 RPM depending on the bearing option

Bearing Life 30,000,000 cycles

Bearings Ball

Run Out .010" max @ .75 from mounting surface

Bushing Mounting Torque 10 in-lb max

Electrical

Current Draw 15 mA (+ output for current loop)
Operating Voltage 5 vdc +/- .26 for .5-4.5 vdc & 0-5 vdc

12.5 – 26 Vdc for current 15-26 Vdc for 0-12 Vdc

Phase Increasing Clockwise

Note: All specifications are specified with Vdc @ nominal input voltage and Ambient Temperature 25 Degrees Celsius.

For current output max loop resistance 700Ω@ 24 Vdc

Mechanical

Axial Load (lbs) 4.5 [20 N] Max. Radial Load (lbs) 2.25 [10 N] Max.

Operating Speed (rpm) 3000

Shaft End Play (in) .005 (.10 Max)

Shaft Radial Play (in) .010 [.25] Max. @ .6 [15.2] from mounting surface

Shaft Push-In Force (lbs) 40 [9N] Shaft Pull-Out Force (lbs) 6 [1.3N]

Environmental

Vibration MIL-STD-202F Method 204D

Test Condition B

Shock MIL-STD-202F Method 213B

Test Condition C

Humidity MIL-STD-202F Method 103B

Test Condition A

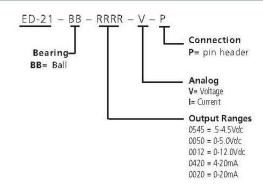
Thermal Shock MIL-STD-202F Method 107G

Test Condition A

Operating Temperature -40C to +85 C Storage Temperature -55C to 125C

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ordering info



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