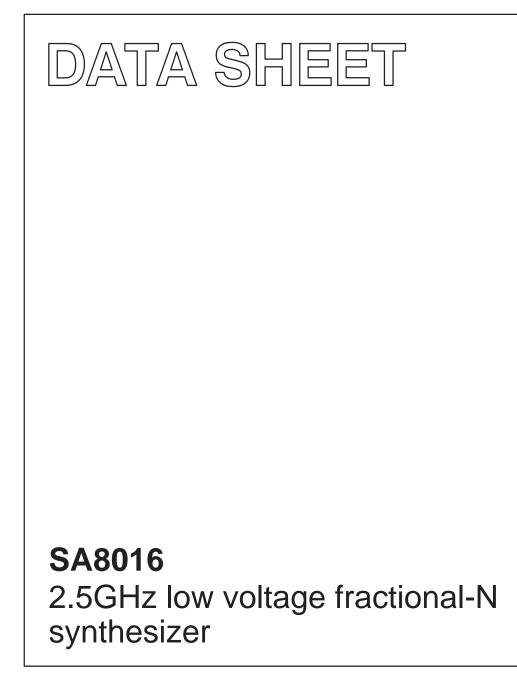
# INTEGRATED CIRCUITS



Product specification Supersedes data of 1999 Apr 16

1999 Nov 04



PHILIPS

Philips Semiconductors

SA8016

#### **GENERAL DESCRIPTION**

The SA8016 BICMOS device integrates programmable dividers, charge pumps and a phase comparator to implement a phase-locked loop. The device is designed to operate from 3 NiCd cells, in pocket phones, with low current and nominal 3 V supplies.

The synthesizer operates at VCO input frequencies up to 2.5 GHz. The synthesizer has fully programmable main and reference dividers. All divider ratios are supplied via a 3-wire serial programming bus.

Separate power and ground pins are provided to the analog and digital circuits. The ground leads should be externally short-circuited to prevent large currents flowing across the die and thus causing damage. V<sub>DDCP</sub> must be greater than or equal to V<sub>DD</sub>.

The charge pump current (gain) is set by an external resistance at the  $R_{SET}$  pin. Only passive loop filters could be used; the charge pump operates within a wide voltage compliance range to provide a wider tuning range.

#### **FEATURES**

- Low phase noise
- Low power
- Fully programmable main divider
- Internal fractional spurious compensation
- Hardware and software power down
- Split supply for V<sub>DD</sub> and V<sub>DDCP</sub>

#### APPLICATIONS

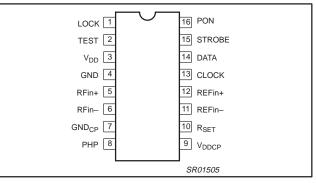
- 350–2500 MHz wireless equipment
- Cellular phones (all standards)
- WLAN
- Portable battery-powered radio equipment.

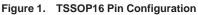
#### QUICK REFERENCE DATA

SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
V <sub>DD</sub>	Supply voltage		2.7	—	5.5	V
V <sub>DDCP</sub>	Analog supply voltage	$V_{DDCP} \ge V_{DD}$	2.7	—	5.5	V
I <sub>DDCP</sub> +I <sub>DD</sub>	Total supply current		—	8.0	9.5	mA
I <sub>DDCP</sub> +I <sub>DD</sub>	Total supply current in power-down mode		—	1	—	μA
f <sub>VCO</sub>	Input frequency		350	—	2500	MHz
f <sub>REF</sub>	Crystal reference input frequency		5	—	40	MHz
f <sub>PC</sub>	Maximum phase comparator frequency		—		4	MHz
T <sub>amb</sub>	Operating ambient temperature		-40	—	+85	°C

#### **ORDERING INFORMATION**

TYPE NUMBER	PACKAGE		
	NAME	DESCRIPTION	VERSION
SA8016DH	TSSOP16	Plastic thin shrink small outline package; 16 leads; body width 4.4 mm	SOT403-1
SA8016WC	HBCC24	Plastic, heatsink bottom chip carrier; 24 terminals; body $4 \times 4 \times 0.65$ mm (CSP package)	SOT564-1





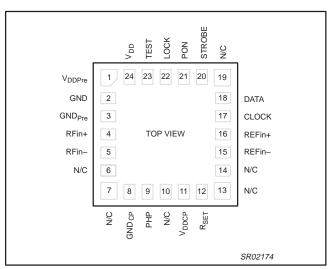
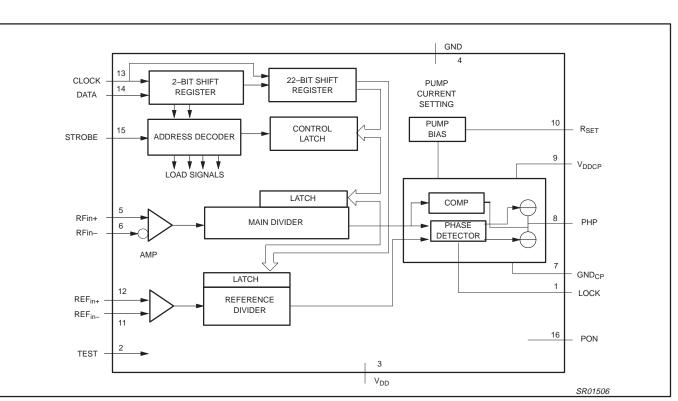


Figure 2. HBCC24 Pin configuration





#### **TSSOP16 PIN DESCRIPTION**

SYMBOL	PIN	DESCRIPTION
LOCK	1	Lock detect output
TEST	2	Test (should be either grounded or connected to V <sub>DD</sub> )
V <sub>DD</sub>	3	Digital supply
GND	4	Digital ground
RFin+	5	RF input to main divider
RFin-	6	RF input to main divider
GND <sub>CP</sub>	7	Charge pump ground
PHP	8	Main normal charge pump
V <sub>DDCP</sub>	9	Charge pump supply voltage
R <sub>SET</sub>	10	External resistor from this pin to ground sets the charge pump current
REFin-	11	Reference input
REFin+	12	Reference input
CLOCK	13	Programming bus clock input
DATA	14	Programming bus data input
STROBE	15	Programming bus enable input
PON	16	Power down control

#### **HBCC24 PIN DESCRIPTION**

SYMBOL	PIN	DESCRIPTION					
V <sub>DDPre</sub>	1	Prescaler supply voltage					
GND	2	Digital ground					
GND <sub>Pre</sub>	3	Prescaler ground					
RFin+	4	RF input to main divider					
RFin-	5	RF input to main divider					
N/C	6	Not connected					
N/C	7	Not connected					
GND <sub>CP</sub>	8	Charge pump ground					
PHP	9	Main normal charge pump					
N/C	10	Not connected					
V <sub>DDCP</sub>	11	Charge pump supply voltage					
R <sub>SET</sub>	12	External resistor from this pin to ground sets the charge pump current					
N/C	13	Not connected					
N/C	14	Not connected					
REFin-	15	Reference input					
REFin+	16	Reference input					
CLOCK	17	Programming bus clock input					
DATA	18	Programming bus data input					
N/C	19	Not connected					
STROBE	20	Programming bus enable input					
PON	21	Power down control					
LOCK	22	Lock detect output					
TEST	23	Test (should be either grounded or connected to V <sub>DD</sub> )					
V <sub>DD</sub>	24	Digital supply					

NOTE:

1. GND<sub>CP</sub> is connected to the die-pad.

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#### LIMITING VALUES

In accordance with the Absolute Maximum Rating System (IEC 134).

SYMBOL	PARAMETER	MIN.	MAX.	UNIT
V <sub>DD</sub>	Digital supply voltage	-0.3	+5.5	V
V <sub>DDCP</sub>	Analog supply voltage	-0.3	+5.5	V
$\Delta V_{DDCP} - V_{DD}$	Difference in voltage between $V_{DDCP and} V_{DD} (V_{DDCP} \ge V_{DD})$	-0.3	+2.8	V
V <sub>n</sub>	Voltage at pins 1, 2, 5, 6, 11 to 16	-0.3	V <sub>DD</sub> + 0.3	V
V <sub>1</sub>	Voltage at pin 8, 9	-0.3	V <sub>DDCP</sub> + 0.3	V
$\Delta V_{GND}$	Difference in voltage between $GND_CP$ and $GND$ (these pins should be connected together)	-0.3	+0.3	V
T <sub>stg</sub>	Storage temperature	-55	+125	°C
T <sub>amb</sub>	Operating ambient temperature	-40	+85	°C
Тj	Maximum junction temperature		150	°C

#### Handling

Inputs and outputs are protected against electrostatic discharge in normal handling. However, to be totally safe, it is desirable to take normal precautions appropriate to handling MOS devices.

#### THERMAL CHARACTERISTICS

SYMBOL	PARAMETER	VALUE	UNIT
R <sub>th j–a</sub> Thermal resistance from junction to ambient in free air		120	K/W

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#### **CHARACTERISTICS**

 $V_{DDCP} = V_{DD} = +3.0V$ ,  $T_{amb} = +25^{\circ}C$ ; unless otherwise specified.

SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
Supply; pir	is 3, 9	•		-	•	
V <sub>DD</sub>	Digital supply voltage		2.7	-	5.5	V
V <sub>DDCP</sub>	Analog supply voltage	$V_{DDCP} = V_{DD}$	2.7	-	5.5	V
I <sub>DDTotal</sub>	Synthesizer operational total supply current	V <sub>DD</sub> = +3.0 V	-	8.0	9.5	mA
I <sub>Standby</sub>	Total supply current in power-down mode	logic levels 0 or V <sub>DD</sub>	-	1		μA
RFin main	divider input; pins 5, 6	•		-		
f <sub>VCO</sub>	VCO input frequency		350	-	2500	MHz
V <sub>RFin(rms)</sub>	AC-coupled input signal level	$\begin{array}{l} R_{\text{in}} \mbox{ (external)} = R_{\text{s}} = 50\Omega;\\ \mbox{single-ended drive;}\\ \mbox{max. limit is indicative}\\ @ 500 \mbox{ to } 2500 \mbox{ MHz} \end{array}$	-18	-	0	dBm
Z <sub>IRFin</sub>	Input impedance (real part)	f <sub>VCO</sub> = 2.4 GHz	-	210	-	Ω
C <sub>IRFin</sub>	Typical pin input capacitance	f <sub>VCO</sub> = 2.4 GHz	-	1.0	-	pF
N <sub>main</sub>	Main divider ratio		512	-	65535	
f <sub>PCmax</sub>	Maximum loop comparison frequency	indicative, not tested	-	-	4	MHz
Reference	divider input; pins 11, 12	•	-	-		-
f <sub>REFin</sub>	Input frequency range from TCXO		5	-	40	MHz
VRFin	AC-coupled input signal level	single-ended drive; max. limit is indicative	360	-	1300	mV <sub>PP</sub>
Z <sub>REFin</sub>	Input impedance (real part)	f <sub>REF</sub> = 20 MHz	-	10	-	kΩ
C <sub>REFin</sub>	Typical pin input capacitance	f <sub>REF</sub> = 20 MHz	-	1.0	-	pF
R <sub>REF</sub>	Reference division ratio		4	-	1023	
Charge pu	np current setting resistor input; pin 10	•		-		
R <sub>SET</sub>	External resistor from pin to ground		6	7.5	15	kΩ
V <sub>SET</sub>	Regulated voltage at pin	R <sub>SET</sub> =7.5 kΩ	-	1.25	-	V
Charge pu	np outputs (including fractional compensation	n pump); pin 8; R <sub>SET</sub> =7.5kΩ, FC	C=80		-	-
I <sub>CP</sub>	Charge pump current ratio to I <sub>SET</sub> <sup>1</sup>	Current gain I <sub>PH</sub> /I <sub>SET</sub>	-15		+15	%
IMATCH	Sink-to-source current matching	V <sub>PH</sub> =1/2 V <sub>DDCP</sub>	-10		+10	%
IZOUT	Output current variation versus V <sub>PH</sub> <sup>2</sup>	V <sub>PH</sub> in compliance range	-10		+10	%
I <sub>LPH</sub>	Charge pump off leakage current	V <sub>PH</sub> =1/2 V <sub>CC</sub>	-10		+10	nA
V <sub>PH</sub>	Charge pump voltage compliance		0.7	-	V <sub>DDCP</sub> -0.8	V

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SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
Phase noi	se (R <sub>SET</sub> = 7.5 kΩ, CP = 00)	•			•	•
	Synthesizer's contribution to close-in phase noise of 900 MHz RF signal at 1 kHz offset.	GSM f <sub>REF</sub> = 13MHz, TCXO,	-	-90	-	dBc/Hz
£ <sub>(f)</sub>	Synthesizer's contribution to close-in phase noise of 1800 MHz RF signal at 1 kHz offset.	f <sub>COMP</sub> = 1MHz indicative, not tested	-	-83	-	dBc/Hz
	Synthesizer's contribution to close-in phase noise of 800 MHz RF signal at 1 kHz offset.	TDMA f <sub>REF</sub> = 19.44MHz, TCXO,	-	-85	-	dBc/Hz
	Synthesizer's contribution to close-in phase noise of 2100 MHz RF signal at 1 kHz offset.	f <sub>COMP</sub> = 240kHz indicative, not tested	-	-77	-	dBc/Hz
Interface I	ogic input signal levels; pins 13, 14, 15, 16	·				
V <sub>IH</sub>	HIGH level input voltage		0.7*V <sub>DD</sub>	_	V <sub>DD</sub> +0.3	V
V <sub>IL</sub>	LOW level input voltage		-0.3	_	0.3*V <sub>DD</sub>	V
I <sub>LEAK</sub>	Input leakage current	logic 1 or logic 0	-0.5	_	+0.5	μA
Lock dete	ct output signal (in push/pull mode); pin 1	•				
V <sub>OL</sub>	LOW level output voltage	I <sub>sink</sub> = 2mA	-	-	0.4	V
V <sub>OH</sub>	HIGH level output voltage	I <sub>source</sub> = -2mA	V <sub>DD</sub> -0.4	_	-	V

NOTES:

1.  $I_{SET} = \frac{V_{SET}}{R_{SET}}$  bias current for charge pumps.

2. The relative output current variation is defined as:

$$\frac{\Delta I_{OUT}}{I_{OUT}} = 2 \cdot \frac{(I_2 - I_1)}{I(I_2 + I_1)I}; \text{ with } V_1 = 0.7V, V_2 = V_{DDCP} - 0.8V \text{ (See Figure 4.)}$$

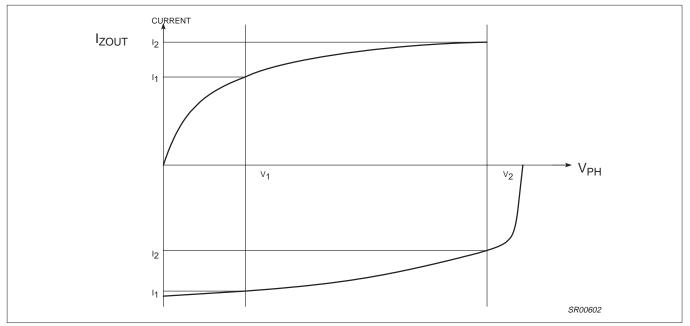


Figure 4. Relative Output Current Variation

#### FUNCTIONAL DESCRIPTION

#### Main Fractional-N divider

The RFin inputs drive a pre-amplifier to provide the clock to the first divider stage. For single ended operation, the signal should be fed to one of the inputs while the other one is AC grounded. The pre-amplifier has a high input impedance, dominated by pin and pad capacitance. The circuit operates with signal levels from –18 dBm to 0 dBm, and at frequencies as high as 2.5 GHz. The divider consists of a fully programmable bipolar prescaler followed by a CMOS counter. Total divide ratios range from 512 to 65536.

At the completion of a main divider cycle, a main divider output pulse is generated which will drive the main phase comparator. Also, the fractional accumulator is incremented by the value of NF. The accumulator works with modulo Q set by FMOD. When the accumulator overflows, the overall division ratio N will be increased by 1 to N + 1, the average division ratio over Q main divider cycles (either 5 or 8) will be

Nfrac = N + 
$$\frac{NF}{Q}$$

The output of the main divider will be modulated with a fractional phase ripple. The phase ripple is proportional to the contents of the

fractional accumulator and is nulled by the fractional compensation charge pump.

The reloading of a new main divider ratio is synchronized to the state of the main divider to avoid introducing a phase disturbance.

#### **Reference divider**

The reference divider consists of a divider with programmable values between 4 and 1023 followed by a three bit binary counter. The 3 bit SM (SA) register (see Figure 5) determines which of the 5 output pulses are selected as the main (auxiliary) phase detector input.

#### Phase detector (see Figure 6)

The reference and main (aux) divider outputs are connected to a phase/frequency detector that controls the charge pump. The pump current is set by an external resistor in conjunction with control bits CP0 and CP1 in the B-word (see Charge Pump table). The dead zone (caused by finite time taken to switch the current sources on or off) is cancelled by forcing the pumps ON for a minimum time at every cycle (backlash time) providing improved linearity.

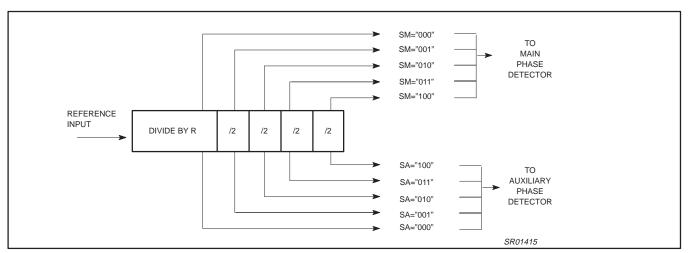


Figure 5. Reference Divider

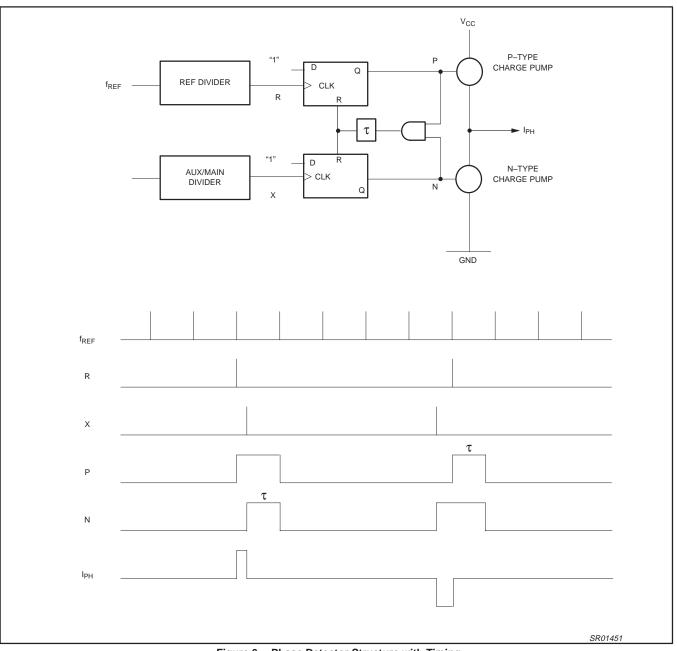


Figure 6. Phase Detector Structure with Timing

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#### Main Output Charge Pumps and Fractional Compensation Currents (see Figure 7)

The main charge pumps on pins PHP and PHI are driven by the main phase detector and the charge pump current values are determined by the current at pin  $R_{SET}$  in conjunction with bits CP0, CP1 in the B-word (see table of charge pump ratios). The fractional compensation is derived from the current at  $R_{SET}$ , the contents of the fractional accumulator FRD and by the program value of the FDAC. The timing for the fractional compensation is derived from the main divider. The main charge pumps will enter speed up mode after the A-word is set and strobe goes High. When strobe goes Low, charge pump will exit speed up mode.

#### **Principle of Fractional Compensation**

The fractional compensation is designed into the circuit as a means of reducing or eliminating fractional spurs that are caused by the fractional phase ripple of the main divider. If  $I_{COMP}$  is the compensation current and  $I_{PUMP}$  is the pump current, then for each charge pump:

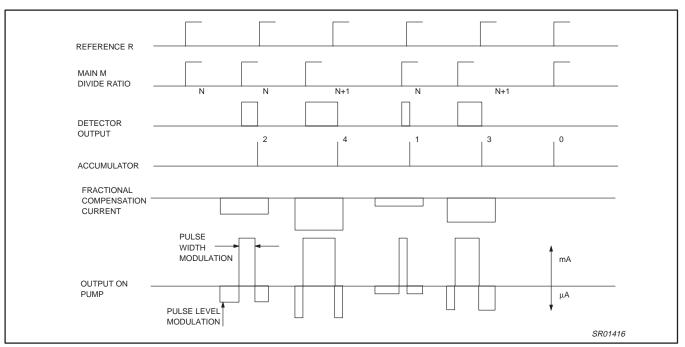
 $I_{PUMP}_{TOTAL} = I_{PUMP} + I_{COMP}$ 

The compensation is done by sourcing a small current,  $I_{COMP}$ , see Figure 8, that is proportional to the fractional error phase. For proper fractional compensation, the area of the fractional compensation current pulse must be equal to the area of the fractional charge pump ripple. The width of the fractional compensation pulse is fixed to 128 VCO cycles, the amplitude is proportional to the fractional accumulator value and is adjusted by FDAC values (bits FC7–0 in the B-word). The fractional compensation current is derived from the main charge pump in that it follows all the current scaling through external resistor setting,  $R_{SET}$ , programming or speed-up operation. For a given charge pump,

I<sub>COMP</sub> = (I<sub>PUMP</sub> / 128) \* (FDAC / 5\*128) \* FRD

FRD is the fractional accumulator value.

The target values for FDAC are: 128 for FMOD = 1 (modulo 5) and 80 for FMOD = 0 (modulo 8).





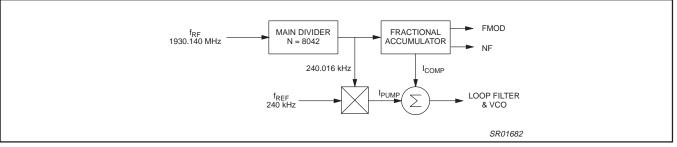


Figure 8. Current Injection Concept

## SA8016

#### Charge pump currents

CP0	I <sub>PHP</sub>	I <sub>PHP-SU</sub>
0	3xI <sub>SET</sub>	15xl <sub>SET</sub>
1	1xl <sub>SET</sub>	5xl <sub>SET</sub>

#### NOTES:

1.  $I_{SET}=V_{SET}/R_{SET}$  bias current for charge pumps.

2. I<sub>PHP-SU</sub> is the total current at pin PHP during speed up condition.

#### Lock Detect

The output LOCK maintains a logic '1' when the auxiliary phase detector ANDed with the main phase detector indicates a lock condition. The lock condition for the main and auxiliary synthesizers is defined as a phase difference of less than  $\pm 1$  period of the frequency at the input REFin+, –. One counter can fulfill the lock condition when the other counter is powered down. Out of lock (logic '0') is indicated when both counters are powered down.

#### Power-down mode

The power-down signal can be either hardware (PON) or software (PD). The PON signal is exclusively ORed with the PD bits in B-word. If PON = 0, then the part is powered up when PD = 1. PON can be used to invert the polarity of the software bit PD. When the synthesizer is reactivated after power-down, the main and reference dividers are synchronized to avoid possibility of random phase errors on power-up.

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#### registers. In order to fully program the synthesizer, 2 words must be sent: B, and A. Table 1 shows the format and the contents of each word. The D word is normally used for testing purposes. When sending the B-word, data bits FC7-0 for the fractional compensation DAC are not loaded immediately. Instead they are stored in temporary registers. Only when the A-word is loaded, these temporary registers are loaded together with the main divider ratio.

data is latched into different working registers or temporary

# 2.5GHz low voltage fractional-N synthesizer

### Serial programming bus

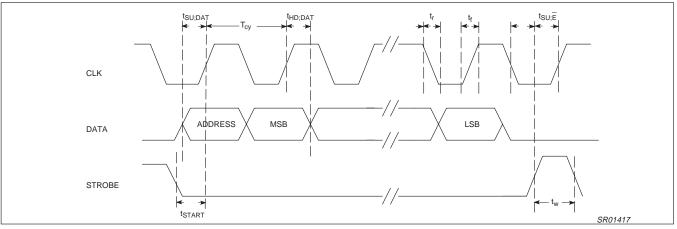
The serial input is a 3-wire input (CLOCK, STROBE, DATA) to program all counter divide ratios, fractional compensation DAC, selection and enable bits. The programming data is structured into 24 bit words; each word includes 2 or 3 address bits. Figure 9 shows the timing diagram of the serial input. When the STROBE goes active HIGH, the clock is disabled and the data in the shift register remains unchanged. Depending on the address bits, the

## Serial bus timing characteristics (See Figure 9)

 $V_{DD} = V_{DDCP} = +3.0V$ ;  $T_{amb} = +25^{\circ}C$  unless otherwise specified.

SYMBOL	PARAMETER	MIN.	TYP.	MAX.	UNIT			
Serial progra								
t <sub>r</sub>	Input rise time	-	10	40	ns			
t <sub>f</sub>	Input fall time	-	10	40	ns			
T <sub>cy</sub>	Clock period	100	-	-	ns			
Enable programming; STROBE								
t <sub>START</sub>	Delay to rising clock edge	40	-	-	ns			
t <sub>W</sub>	Minimum inactive pulse width	1/f <sub>COMP</sub>	-	-	ns			
t <sub>SU;E</sub>	Enable set-up time to next clock edge	20	-	-	ns			
Register ser	al input data; DATA							
t <sub>SU;DAT</sub>	Input data to clock set-up time	20	-	-	ns			
t <sub>HD;DAT</sub>	Input data to clock hold time	20	-	_	ns			

### Application information



#### Figure 9. Serial Bus Timing Diagram

## SA8016

#### Data format

#### Table 1. Format of programmed data

LAST IN		MSB		SERIAL PROGRAMMING FORMAT							
p23	p22	p21	p20	/	/	р1	p0				

## Table 2. A word, length 24 bits

LAST	IN					MSB															LSB	FIRST IN		
Address fmod Fractional-N				-N	Main D	ivider	ratio														Sp	oare		
0	0	FM	NF2	NF1	NF0	N15	N14	N13	N12	N11	N10	N9	N8	N7	N6	N5	N4	N3	N2	N1	N0	SP1	SP2	
Defa	ult:	0	0	1	0	0	0	1	0	0	0	1	0	0	0	1	1	0	0	0	0	0	0	
A wor	d sele	ct			Fixed	to 00.																		
Fracti	onal N	lodulus	selec	t	FM 0	= modu	lo 8, 1	= mo	odulo	5.														
Fractional-N Increment NF20 Fractional N Increment values 000 to 111.																								
N-Divider N0N15, Main divider values 512 to 65535 allowed for divider ratio.																								

### Table 3. B word, length 24 bits

Add	ress			I	REFE	RENC	E DI	/IDER	2			LOCK	PD	СР	FF	RACT	IONA		MPEN	SATIO	ON DA	AC	SPARE
0	1	R9	R8	R7	R6	R5	R4	R3	R2	R1	R0	LO	MAIN	CP0	FC7	FC6	FC5	FC4	FC3	FC2	FC1	FC0	SP3
Defa	ault:	0	0	0	1	0	1	0	0	0	1	0	0	0	0	1	0	1	0	0	0	0	0
B word select Fixed to 01						ixed to 01																	
R-Di	R-Divider				R0R9, Reference divider values 4 to 1023 allowed for divider ration.																		
Char Ratio	arge pump current CP0: Charge pump current ratio, see table of charge pump currents.																						
Lock	detec	t outp	t output b L0 c Main lock detect signal present at the LOCK pin (push/pull). c Main lock detect signal present at the LOCK pin (open drain). When main loop is in power down mode, the lock indicator is low.																				
Powe	er dow	/n			Main	ı = 1: ı	power	to ma	ain div	/ider,	refere	ence divi	der, ma	ain cha	arge p	umps	, Main	= 0 to	o powe	er dow	/n.		
Frac	tional	Comp	ensat	tion	FC7	0 Fra	actiona	al Cor	npens	sation	charg	ge pump	curren	t DAC	, valu	es 0 to	255.						

### Table 4. D word, length 24 bits

· ·	Addre	es	s	S	YNTH	ESIZE BITS		ST							SYN	THES	IZER <sup>-</sup>	TEST	BITS					
1	1	Т	0	-	-	-	-	-	Tspu	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
	Defau	ult:		0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
Tsp	Tspu: Speed up = 1 Forces the r NOTE: All te															me.								

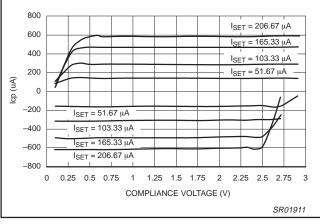


Figure 10. Php Charge Pump Output vs.  $I_{SET}$ (CP = 0, TEMP = 25°C)

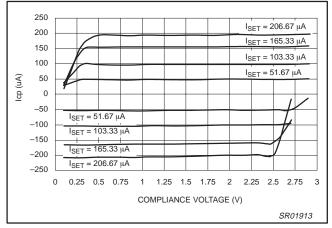


Figure 12. Php Charge Pump Output vs.  $I_{SET}$ (CP = 1; TEMP = 25°C)

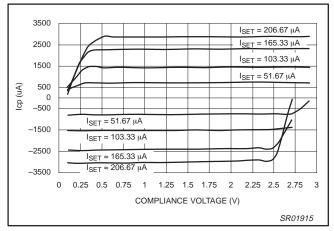


Figure 14. Php-su Charge Pump Output vs. I<sub>SET</sub> (CP = 0; TEMP = 25°C)

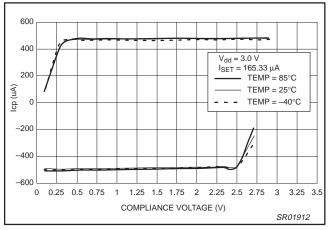


Figure 11. Php Charge Pump Output vs. Temperature (CP = 0;  $V_{DD}$  = 3.0 V; I<sub>SET</sub> = 165.33  $\mu$ A)

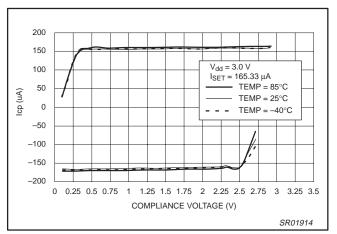


Figure 13. Php Charge Pump Output vs. Temperature (CP = 1;  $V_{DD}$  = 3.0 V;  $I_{SET}$  = 165.33  $\mu$ A)

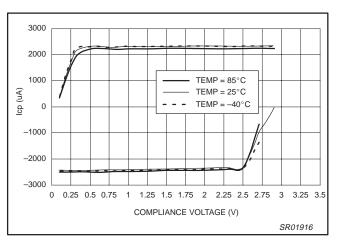
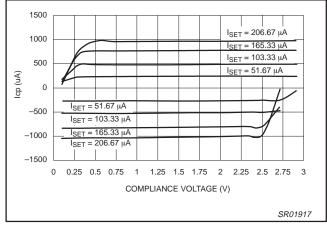


Figure 15. Php–su Charge Pump Output vs. Temperature (CP = 0;  $V_{DD}$  = 3.0 V;  $I_{SET}$  = 165.33  $\mu$ A)





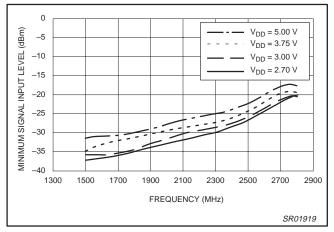


Figure 18. Main Divider Input Sensitivity vs. Frequency and Supply Voltage (TEMP = 25°C)

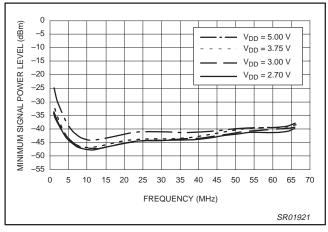


Figure 20. Reference Divider Input Sensitivity vs. Frequency and Supply Voltage (TEMP = 25°C)

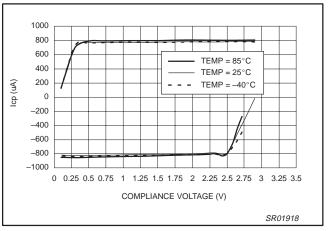


Figure 17. Php–su Charge Pump Output vs. Temperature (CP = 1;  $V_{DD}$  = 3.0 V;  $I_{SET}$  = 165.33  $\mu$ A)

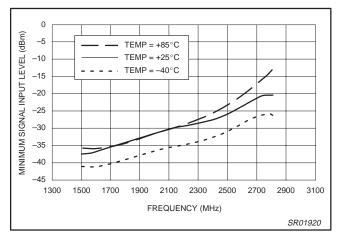


Figure 19. Main Divider Input Sensitivity vs. Frequency and Temperature ( $V_{DD} = 3.00 \text{ V}$ )

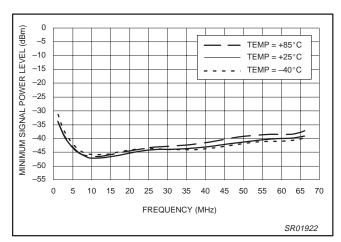


Figure 21. Reference Divider Input Sensitivity vs. Frequency and Temperature (V<sub>DD</sub> = 3.00 V)

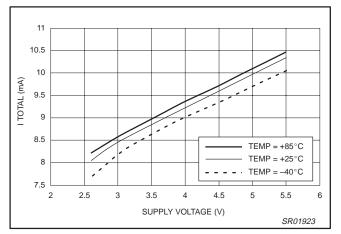
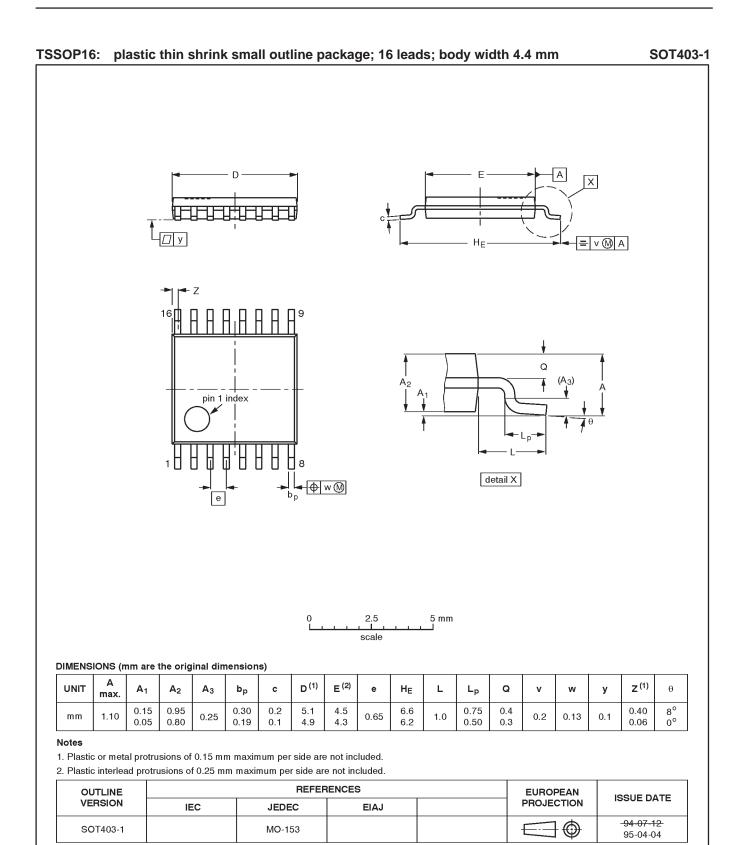


Figure 22. Current Supply Over V<sub>DD</sub>

## Product specification

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ma	A ax.	<b>A</b> <sub>1</sub>		<b>b</b> 0.35 0.20	<b>b</b> 1 0.50 0.30	<b>b</b> 2 0.50 0.35	0.50	4.1 3.9	2.2 2.0	4.1 3.9	2.2 2.0	0.5	3.2	3.2	3.15	3.15	0.2	0.15	0.15	0.05



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SA8016

NOTES

## SA8016

#### Data sheet status

Data sheet status	Product status	Definition [1]
Objective specification	Development	This data sheet contains the design target or goal specifications for product development. Specification may change in any manner without notice.
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[1] Please consult the most recently issued datasheet before initiating or completing a design.

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Date of release: 11-99

Document order number:

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