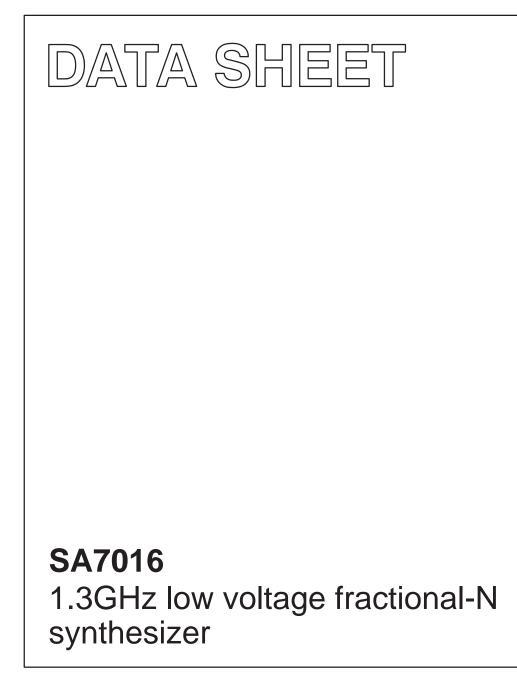
INTEGRATED CIRCUITS



Product specification Supersedes data of 1999 Apr 20

1999 Nov 04



Philips Semiconductors

GENERAL DESCRIPTION

The SA7016 BICMOS device integrates programmable dividers, charge pumps and a phase comparator to implement a phase-locked loop. The device is designed to operate from 3 NiCd cells, in pocket phones, with low current and nominal 3 V supplies.

The synthesizer operates at VCO input frequencies up to 1.3 GHz. The synthesizer has fully programmable main and reference dividers. All divider ratios are supplied via a 3-wire serial programming bus.

Separate power and ground pins are provided to the analog and digital circuits. The ground leads should be externally short-circuited to prevent large currents flowing across the die and thus causing damage. V_{DDCP} must be greater than or equal to V_{DD}.

The charge pump current (gain) is set by an external resistance at the RSET pin. Only passive loop filters could be used; the charge pump operates within a wide voltage compliance range to provide a wider tuning range.

FEATURES

- Low phase noise
- Low power
- Fully programmable main divider
- Internal fractional spurious compensation
- Hardware and software power down
- Split supply for V_{DD} and V_{DDCP}

QUICK REFERENCE DATA

SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
V _{DD}	Supply voltage		2.7	-	5.5	V
V _{DDCP}	Analog supply voltage	$V_{DDCP} \ge V_{DD}$	2.7	-	5.5	V
I _{DDCP} +I _{DD}	Total supply current		-	6.2	7.3	mA
I _{DDCP} +I _{DD}	Total supply current in power-down mode		-	1	-	μA
f _{VCO}	Input frequency		350	-	1300	MHz
f _{REF}	Crystal reference input frequency		5	-	40	MHz
f _{PC}	Maximum phase comparator frequency		-		4	MHz
T _{amb}	Operating ambient temperature		-40	-	+85	°C

APPLICATIONS

Cellular phones

• 350-1300 MHz wireless equipment

• Portable battery-powered radio equipment.

ORDERING INFORMATION

TYPE NUMBER	PACKAGE		
	NAME	DESCRIPTION	VERSION
SA7016DH	TSSOP16	Plastic thin shrink small outline package; 16 leads; body width 4.4 mm	SOT403-1

2

16 PON LOCK 1 TEST 2 15 STROBE V_{DD} 3 14 DATA 13 CLOCK GND 4 RFin+ 5 12 REFin+ 11 REFin-RFin- 6 GND_{CP} 7 10 R_{SET} 9 V_{DDCP} PHP 8 SR01505

Figure 1. Pin Configuration

SA7016

1.3GHz low voltage fractional-N synthesizer

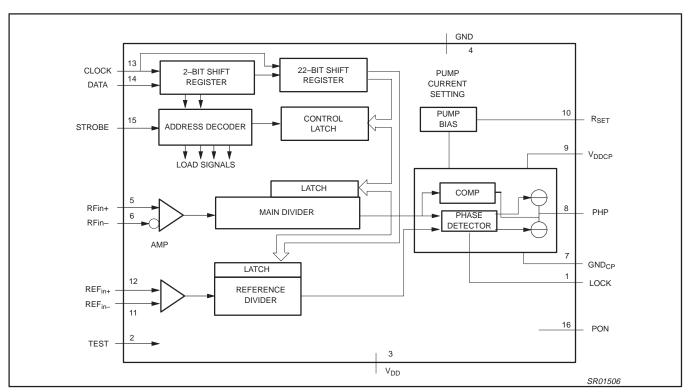


Figure 2. Block Diagram

PINNING

SYMBOL	PIN	DESCRIPTION
LOCK	1	Lock detect output
TEST	2	Test (should be either grounded or connected to V _{DD)}
V _{DD}	3	Digital supply
GND	4	Digital ground
RFin+	5	RF input to main divider
RFin-	6	RF input to main divider
GND _{CP}	7	Charge pump ground
PHP	8	Main normal chargepump
V _{DDCP}	9	Charge pump supply voltage
R _{SET}	10	External resistor from this pin to ground sets the chargepump current
REFin-	11	Reference input
REFin+	12	Reference input
CLOCK	13	Programming bus clock input
DATA	14	Programming bus data input
STROBE	15	Programming bus enable input
PON	16	Power down control

1999 Nov 04

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LIMITING VALUES

In accordance with the Absolute Maximum Rating System (IEC 134).

SYMBOL	PARAMETER	MIN.	MAX.	UNIT
V _{DD}	Digital supply voltage	-0.3	+5.5	V
V _{DDCP}	Analog supply voltage	-0.3	+5.5	V
$\Delta V_{DDCP} - V_{DD}$	Difference in voltage between $V_{DDCP and} V_{DD} (V_{DDCP} \ge V_{DD})$	-0.3	+2.8	V
V _n	Voltage at pins 1, 2, 5, 6, 11 to 16	-0.3	V _{DD} + 0.3	V
V ₁	Voltage at pin 8, 9	-0.3	V _{DDCP} + 0.3	V
ΔV_{GND}	Difference in voltage between GND_CP and GND (these pins should be connected together)	-0.3	+0.3	V
T _{stg}	Storage temperature	-55	+125	°C
T _{amb}	Operating ambient temperature	-40	+85	°C
Тj	Maximum junction temperature		150	°C

Handling

Inputs and outputs are protected against electrostatic discharge in normal handling. However, to be totally safe, it is desirable to take normal precautions appropriate to handling MOS devices.

THERMAL CHARACTERISTICS

SYMBOL	PARAMETER	VALUE	UNIT
R _{th j–a}	Thermal resistance from junction to ambient in free air	120	K/W

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CHARACTERISTICS

 $V_{DDCP} = V_{DD} = +3.0V$, $T_{amb} = +25^{\circ}C$; unless otherwise specified.

SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
Supply; pir	ns 3, 9	•			•	
V _{DD}	Digital supply voltage		2.7	-	5.5	V
V _{DDCP}	Analog supply voltage	$V_{DDCP} = V_{DD}$	2.7	-	5.5	V
I _{DDTotal}	Synthesizer operational total supply current	V _{DD} = +3.0V	-	6.2	7.3	mA
I _{Standby}	Total supply current in power-down mode	logic levels 0 or VDD	-	1	TBD	μA
RFin main	divider input; pins 5, 6	-				-
f _{VCO}	VCO input frequency		350	-	1300	MHz
V _{RFin(rms)}	AC-coupled input signal level	R_{in} (external) = $R_s = 50\Omega$; single-ended drive; max. limit is indicative @ 500 to 1300 MHz	-18	-	0	dBm
Z _{IRFin}	Input impedance (real part)	f _{VCO} = 1.2 GHz	-	625	-	Ω
C _{IRFin}	Typical pin input capacitance	f _{VCO} = 1.2 GHz	-	1.0	-	pF
N _{main}	Main divider ratio		512	-	65535	
f _{PCmax}	Maximum loop comparison frequency	indicative, not tested	-	-	4	MHz
Reference	divider input; pins 11, 12					
f _{REFin}	Input frequency range from TCXO		5	-	40	MHz
VRFin	AC-coupled input signal level	single-ended drive; max. limit is indicative	360	-	1300	mV _{PP}
Z _{REFin}	Input impedance (real part)	f _{REF} = 20 MHz	-	10	-	kΩ
C _{REFin}	Typical pin input capacitance	f _{REF} = 20 MHz	-	1.0	-	pF
R _{REF}	Reference division ratio		4	-	1023	
Charge pu	mp current setting resistor input; pin 10					
R _{SET}	External resistor from pin to ground		6	7.5	15	kΩ
V _{SET}	Regulated voltage at pin	R _{SET} =7.5 kΩ	-	1.25	-	V
Charge pu	mp outputs (including fractional compensation	n pump); pin 8; R _{SET} =7.5kΩ, FC	2=80			
I _{CP}	Charge pump current ratio to I _{SET} ¹	Current gain I _{PH} /I _{SET}	-15		+15	%
IMATCH	Sink-to-source current matching	V _{PH} =1/2 V _{DDCP} .	-10		+10	%
I _{ZOUT}	Output current variation versus V _{PH} ²	V _{PH} in compliance range	-10		+10	%
I _{LPH}	Charge pump off leakage current	V _{PH} =1/2 V _{CC}	-10		+10	nA
V _{PH}	Charge pump voltage compliance		0.7	-	V _{DDCP} -0.8	V

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SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
Phase noi	se (R _{SET} = 7.5 kΩ, CP=00)		•		•	
	Synthesizer's contribution to close-in phase noise of 900 MHz RF signal at 1 kHz offset.	GSM f _{REF} = 13MHz, TCXO,	-	-90	-	dBc/Hz
0		f _{COMP} = 1MHz indicative, not tested				
L _(f)	Synthesizer's contribution to close-in phase noise of 800 MHz RF signal at 1 kHz offset.	TDMA f _{REF} = 19.44MHz, TCXO, f _{COMP} = 240kHz indicative, not tested	-	-85	_	dBc/Hz
Interface l	ogic input signal levels; pins 13, 14, 15, 16					
V _{IH}	HIGH level input voltage		0.7*V _{DD}	-	V _{DD} +0.3	V
V _{IL}	LOW level input voltage		-0.3	-	0.3*V _{DD}	V
I _{LEAK}	Input leakage current	logic 1 or logic 0	-0.5	-	+0.5	μΑ
Lock dete	ct output signal (in push/pull mode); pin 1					
V _{OL}	LOW level output voltage	I _{sink} =2mA	-	-	0.4	V
V _{OH}	HIGH level output voltage	I _{source} =-2mA	V _{DD} -0.4	-	-	V

NOTES:

1. $I_{SET} = \frac{V_{SET}}{R_{SET}}$ bias current for charge pumps.

2. The relative output current variation is defined as:

$$\frac{\Delta I_{OUT}}{I_{OUT}} = 2 \cdot \frac{(I_2 - I_1)}{I(I_2 + I_1)I}; \text{ with } V_1 = 0.7V, V_2 = V_{DDCP} - 0.8V \text{ (See Figure 3.)}$$

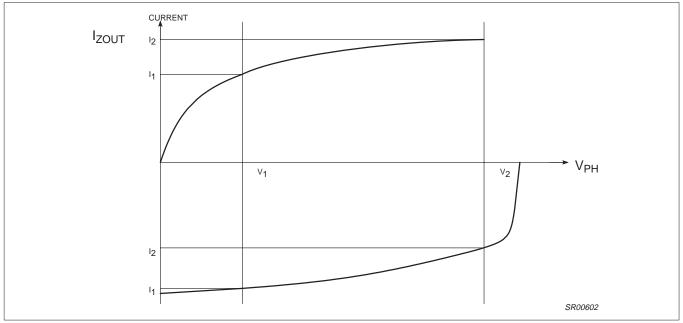


Figure 3. Relative Output Current Variation

FUNCTIONAL DESCRIPTION

Main Fractional-N divider

The RFin inputs drive a pre-amplifier to provide the clock to the first divider stage. For single ended operation, the signal should be fed to one of the inputs while the other one is AC grounded. The pre-amplifier has a high input impedance, dominated by pin and pad capacitance. The circuit operates with signal levels from –18 dBm to 0 dBm, and at frequencies as high as 1.3 GHz. The divider consists of a fully programmable bipolar prescaler followed by a CMOS counter. Total divide ratios range from 512 to 65536.

At the completion of a main divider cycle, a main divider output pulse is generated which will drive the main phase comparator. Also, the fractional accumulator is incremented by the value of NF. The accumulator works with modulo Q set by FMOD. When the accumulator overflows, the overall division ratio N will be increased by 1 to N + 1, the average division ratio over Q main divider cycles (either 5 or 8) will be

Nfrac = N +
$$\frac{NF}{Q}$$

The output of the main divider will be modulated with a fractional phase ripple. The phase ripple is proportional to the contents of the

fractional accumulator and is nulled by the fractional compensation charge pump.

The reloading of a new main divider ratio is synchronized to the state of the main divider to avoid introducing a phase disturbance.

Reference divider

The reference divider consists of a divider with programmable values between 4 and 1023 followed by a three bit binary counter. The 3 bit SM (SA) register (see Figure 4) determines which of the 5 output pulses are selected as the main (auxiliary) phase detector input.

Phase detector (see Figure 5)

The reference and main (aux) divider outputs are connected to a phase/frequency detector that controls the charge pump. The pump current is set by an external resistor in conjunction with control bits CP0 and CP1 in the C-word (see Charge Pump table). The dead zone (caused by finite time taken to switch the current sources on or off) is cancelled by forcing the pumps ON for a minimum time at every cycle (backlash time) providing improved linearity.

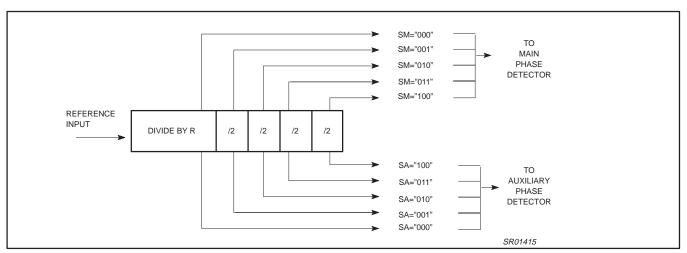


Figure 4. Reference Divider

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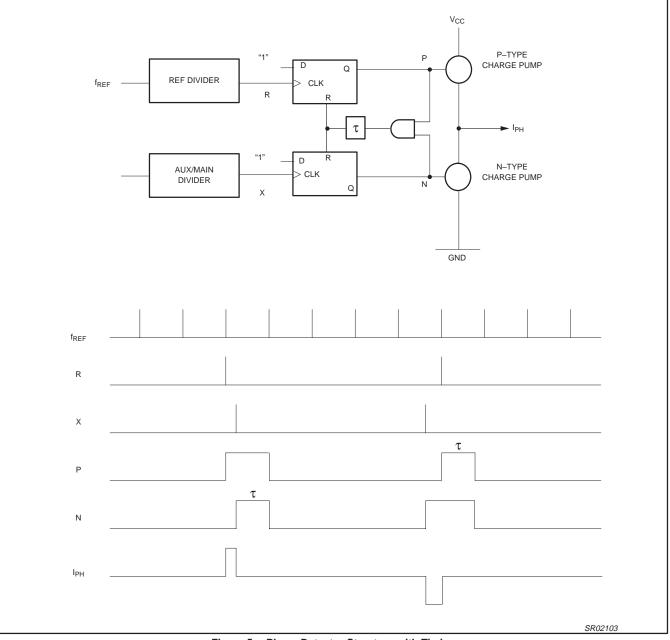


Figure 5. Phase Detector Structure with Timing

Product specification

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Main Output Charge Pumps and Fractional Compensation Currents (see Figure 6)

The main charge pumps on pins PHP and PHI are driven by the main phase detector and the charge pump current values are determined by the current at pin R_{SET} in conjunction with bits CP0, CP1 in the B-word (see table of charge pump ratios). The fractional compensation is derived from the current at R_{SET} , the contents of the fractional accumulator FRD and by the program value of the FDAC. The timing for the fractional compensation is derived from the main divider. The main charge pumps will enter speed up mode after the A-word is set and strobe goes High. When strobe goes Low, charge pump will exit speed up mode.

Principle of Fractional Compensation

The fractional compensation is designed into the circuit as a means of reducing or eliminating fractional spurs that are caused by the fractional phase ripple of the main divider. If I_{COMP} is the compensation current and I_{PUMP} is the pump current, then for each charge pump:

fractional compensation, the area of the fractional compensation current pulse must be equal to the area of the fractional charge pump ripple. The width of the fractional compensation pulse is fixed to 128 VCO cycles, the amplitude is proportional to the fractional accumulator value and is adjusted by FDAC values (bits FC7–0 in the B-word). The fractional compensation current is derived from the main charge pump in that it follows all the current scaling through external resistor setting, R_{SET} , programming or speed-up operation. For a given charge pump,

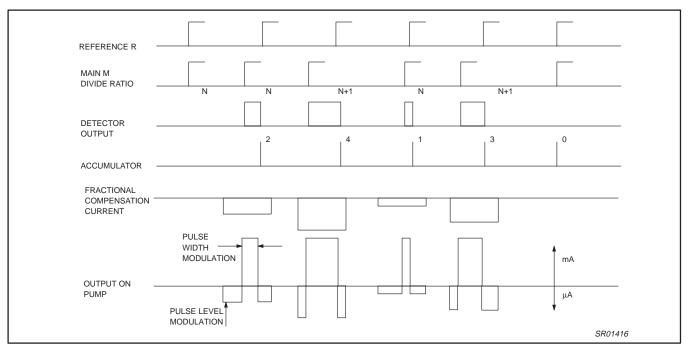
The compensation is done by sourcing a small current, I_{COMP} , see

Figure 7, that is proportional to the fractional error phase. For proper

I_{COMP} = (I_{PUMP} / 128) * (FDAC / 5*128) * FRD

FRD is the fractional accumulator value.

The target values for FDAC are: 128 for FMOD = 1 (modulo 5) and 80 for FMOD = 0 (modulo 8).





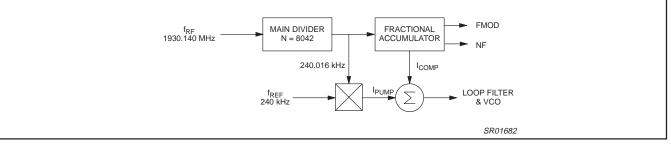


Figure 7. Current Injection Concept

9

IPUMP TOTAL = IPUMP + ICOMP.

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Charge pump currents

CP0	I _{PHP}	I _{PHP-SU}
0	3xI _{SET}	15xl _{SET}
1	1xl _{SET}	5xl _{SET}

NOTES:

1. $I_{SET}=V_{SET}/R_{SET}$ bias current for charge pumps.

I_{PHP-SU} is the total current at pin PHP during speed up condition.

Lock Detect

The output LOCK maintains a logic '1' when the auxiliary phase detector ANDed with the main phase detector indicates a lock condition. The lock condition for the main and auxiliary synthesizers is defined as a phase difference of less than ± 1 period of the frequency at the input REFin+, –. One counter can fulfill the lock condition when the other counter is powered down. Out of lock (logic '0') is indicated when both counters are powered down.

Power-down mode

The power-down signal can be either hardware (PON) or software (PD). The PON signal is exclusively ORed with the PD bits in B-word. If PON = 0, then the part is powered up when PD = 1. PON can be used to invert the polarity of the software bit PD. When the synthesizer is reactivated after power-down, the main and reference dividers are synchronized to avoid possibility of random phase errors on power-up.

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Serial programming bus

The serial input is a 3-wire input (CLOCK, STROBE, DATA) to program all counter divide ratios, fractional compensation DAC, selection and enable bits. The programming data is structured into 24 bit words; each word includes 2 or 3 address bits. Figure 8 shows the timing diagram of the serial input. When the STROBE goes active HIGH, the clock is disabled and the data in the shift register remains unchanged. Depending on the address bits, the data is latched into different working registers or temporary registers. In order to fully program the synthesizer, 3 words must be sent: C, B, and A. Table 1 shows the format and the contents of each word. The D word is normally used for testing purposes. When sending the B-word, data bits FC7–0 for the fractional compensation DAC are not loaded immediately. Instead they are stored in temporary registers. Only when the A-word is loaded, these temporary registers are loaded together with the main divider ratio.

Serial bus timing characteristics. See Figure 8.

 $V_{DD} = V_{DDCP} = +3.0V$; $T_{amb} = +25^{\circ}C$ unless otherwise specified.

SYMBOL	PARAMETER	MIN.	TYP.	MAX.	UNIT
Serial programm	ing clock; CLK				
t _r	Input rise time	-	10	40	ns
t _f	Input fall time	-	10	40	ns
T _{cy}	Clock period	100	-	-	ns
Enable programm	ning; STROBE				
t _{START}	Delay to rising clock edge	40	-	-	ns
t _W	Minimum inactive pulse width	1/f _{COMP}	-	-	ns
t _{SU;E}	Enable set-up time to next clock edge	20	-	-	ns
Register serial in	put data; DATA				
t _{SU;DAT}	Input data to clock set-up time	20	-	-	ns
t _{HD;DAT}	Input data to clock hold time	20	-	-	ns

Application information

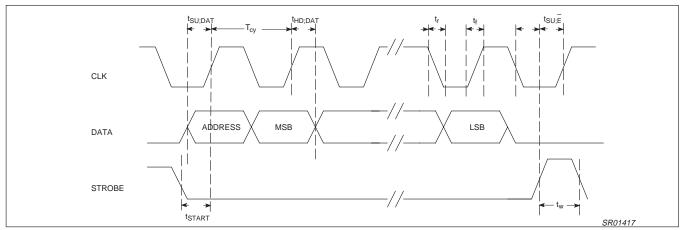


Figure 8. Serial Bus Timing Diagram

SA7016

Data format

Table 1. Format of programmed data

LAST IN		MSB		SERIAL PROGRA	MMING FORMAT		FIRST IN LSB
p23	p22	p21	p20	/	/	р1	p0

Table 2. A word, length 24 bits

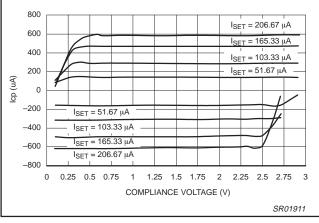
LAST	IN					MSB															FIR	ST IN	
Addre	Address fmod Fractional-N				-N	Main Divider ratio															Sp	oare	
0	0	FM	NF2	NF1	NF0	N15	N15 N14 N13 N12 N11 N10 N9 N8 N7 N6 N5 N4 N3 N2 N1 N0									N0	SP1	SP2					
Defa	Default: 0 0 1 0						0	1	0	0	0	1	0	0	0	1	1	0	0	0	0	0	0
A wor	d sele	ct			Fixed	Fixed to 00.																	
Fracti	onal N	lodulus	selec	t	FM 0	FM 0 = modulo 8, 1 = modulo 5.																	
Fracti	onal-N	Increm	nent		NF2	0 Fractio	onal N	Incre	ement	value	es 000	to 11	1.										
N-Div	ider				N0N	N0N15, Main divider values 512 to 65535 allowed for divider ratio.																	

Table 3. B word, length 24 bits

Add	ress			F	REFE	RENC	E DI	/IDER	2			LOCK	PD	СР	FF	RACT	IONA	L COI	MPEN	SATIO	ON DA	AC	SPARE
0	1	R9	R8	R7	R6	R5	R5 R4 R3 R2 R1 R0 LO MAIN CP0 FC7 FC6 FC5 FC4 FC3 FC2 FC1 FC0 SP2											SP3					
Defa	ault:	0	0	0	1	0	1	0	0	0	1	0	0	0	0	1	0	1	0	0	0	0	0
B wo	rd sel	ect	-		Fixe	d to 0	1													-		-	
R-Di	vider				R0I	R9, Reference divider values 4 to 1023 allowed for divider ration.																	
Char Ratio	ge pu	mp cı	urrent		CP0	P0: Charge pump current ratio, see table of charge pump currents.																	
Lock	detec	t outp	out		1 N	/lain lo	ock de	tect s	ignal	, prese	nt at t	he LOC he LOC le, the lo	K pin (c	pen d	rain).								
Powe	er dow	/n			Main	Main = 1: power to main divider, reference divider, main charge pumps, Main = 0 to power down.																	
Frac	tional	Comp	ensat	tion FC70 Fractional Compensation charge pump current DAC, values 0 to 255.																			

Table 4. D word, length 24 bits

Address				SYNTHESIZER TEST BITS						SYNTHESIZER TEST BITS														
1	1	Т	0	-	-	-	-	-	Tspu	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
	Defau	ult:		0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
Tsp								in charge pumps in speed-up mode all the time. bits must be set to 0 for normal operation.																





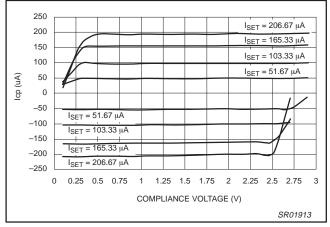


Figure 11. Php Charge Pump Output vs. I_{SET} (CP = 1; TEMP = 25°C)

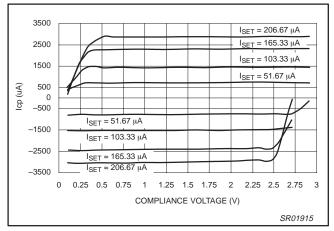


Figure 13. Php-su Charge Pump Output vs. I_{SET} (CP = 0; TEMP = 25°C)

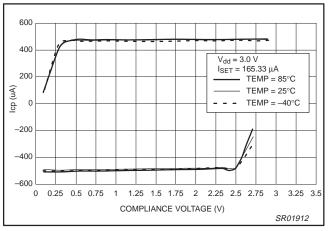


Figure 10. Php Charge Pump Output vs. Temperature (CP = 0; V_{DD} = 3.0 V; I_{SET} = 165.33 μ A)

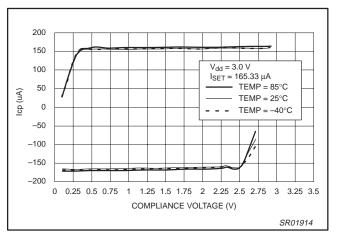


Figure 12. Php Charge Pump Output vs. Temperature (CP = 1; V_{DD} = 3.0 V; I_{SET} = 165.33 μ A)

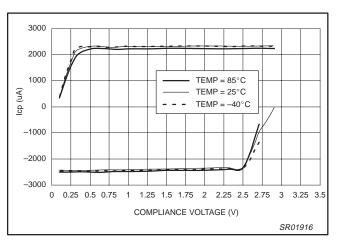
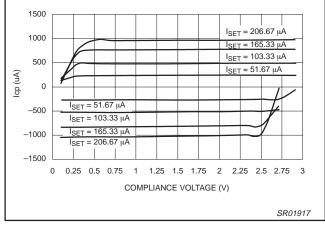


Figure 14. Php–su Charge Pump Output vs. Temperature (CP = 0; V_{DD} = 3.0 V; I_{SET} = 165.33 μ A)





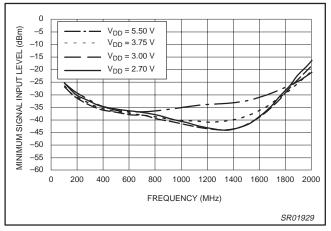


Figure 17. Main Divider Input Sensitivity vs. Frequency and Supply Voltage (TEMP = 25° C)

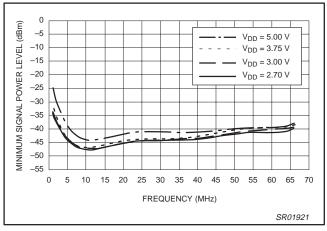


Figure 19. Reference Divider Input Sensitivity vs. Frequency and Supply Voltage (TEMP = 25°C)

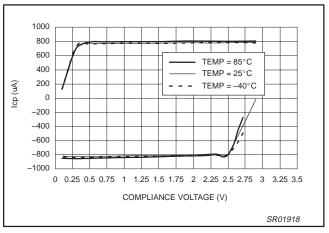


Figure 16. Php–su Charge Pump Output vs. Temperature (CP = 1; V_{DD} = 3.0 V; I_{SET} = 165.33 μ A)

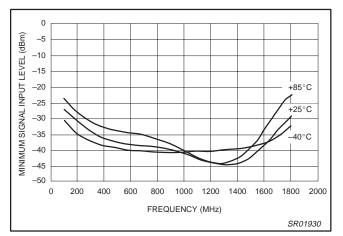


Figure 18. Main Divider Input Sensitivity vs. Frequency and Temperature ($V_{DD} = 3.00 \text{ V}$)

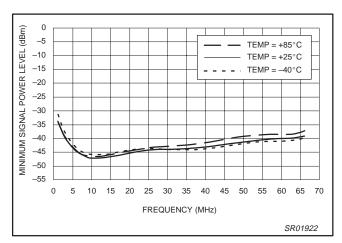


Figure 20. Reference Divider Input Sensitivity vs. Frequency and Temperature (V_{DD} = 3.00 V)

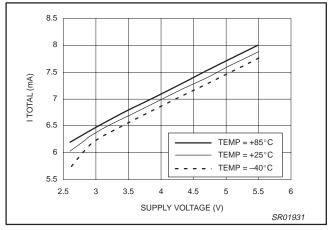
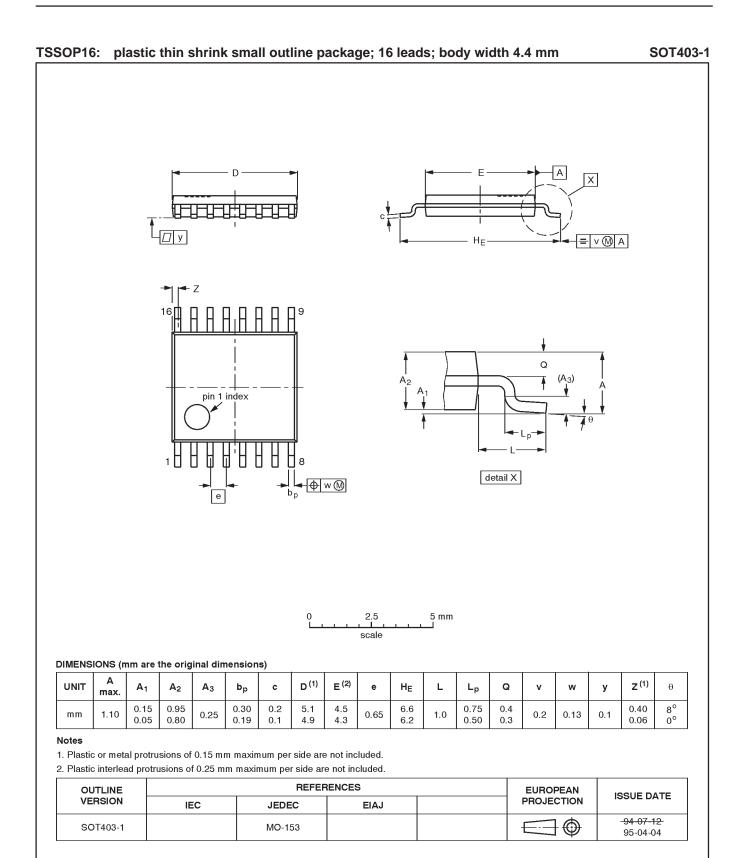


Figure 21. Current Supply Over V_{DD}

synthesizer



Product specification

1.3GHz low voltage fractional-N frequency synthesizer

Data sheet status

Data sheet status	Product status	Definition [1]
Objective specification	Development	This data sheet contains the design target or goal specifications for product development. Specification may change in any manner without notice.
Preliminary specification	Qualification	This data sheet contains preliminary data, and supplementary data will be published at a later date. Philips Semiconductors reserves the right to make chages at any time without notice in order to improve design and supply the best possible product.
Product specification	Production	This data sheet contains final specifications. Philips Semiconductors reserves the right to make changes at any time without notice in order to improve design and supply the best possible product.

[1] Please consult the most recently issued datasheet before initiating or completing a design.

Definitions

Short-form specification — The data in a short-form specification is extracted from a full data sheet with the same type number and title. For detailed information see the relevant data sheet or data handbook.

Limiting values definition — Limiting values given are in accordance with the Absolute Maximum Rating System (IEC 134). Stress above one or more of the limiting values may cause permanent damage to the device. These are stress ratings only and operation of the device at these or at any other conditions above those given in the Characteristics sections of the specification is not implied. Exposure to limiting values for extended periods may affect device reliability.

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