

## Letter Symbols - FETs

## General

### LETTER SYMBOLS

The letter symbols for transistors detailed in this section are based on IEC publication number 148.

#### Basic letters

In the representation of currents, voltages and powers, lower-case letter symbols are used to indicate all instantaneous values that vary with time. All other values are represented by upper-case letters.

Electrical parameters<sup>(1)</sup> of external circuits and of circuits in which the device forms only a part are represented by upper-case letters. Lower-case letters are used for the representation of electrical parameters inherent in the device. Inductances and capacitances are always represented by upper-case letters.

The following is a list of basic letter symbols used with semiconductor devices:

B, b	susceptance (imaginary part of an admittance)
C	capacitance
G, g	conductance (real part of an admittance)
H, h	hybrid parameter
I, i	current
L	inductance
P, p	power
R, r	resistance (real part of an impedance)
V, v	voltage
X, x	reactance (imaginary part of an impedance)
Y, y	admittance
Z, z	impedance

#### Subscripts

Upper-case subscripts are used for the indication of:

- continuous (DC) values (without signal), e.g.  $I_D$
- instantaneous total values, e.g.  $i_D$
- average total values, e.g.  $I_{D(AV)}$
- peak total values, e.g.  $I_{DM}$
- root-mean-square total values, e.g.  $I_{D(RMS)}$ .

Lower-case subscripts are used for the indication of values applying to the varying component alone:

- instantaneous values, e.g.  $i_b$

- root-mean-square values, e.g.  $I_{d(rms)}$
- peak values, e.g.  $I_{dm}$
- average values, e.g.  $I_{d(av)}$ .

The following is a list of subscripts used with basic letter symbols for semiconductor devices:

A, a	anode
amb	ambient
(AV), (av)	average value
B, b	base
(BO)	breakover
(BR)	breakdown
case	case
C, c	collector
C	controllable
D, d	drain
E, e	emitter
F, f	fall, forward (or forward transfer)
G, g	gate
H	holding
h	heatsink
I, i	input
j-a	junction to ambient
j-mb	junction to mounting base
K, k	cathode
L	load
M, m	peak value
(min)	minimum
(max)	maximum
mb	mounting base
O, o	as third subscript: the terminal not mentioned is open-circuit
(OV)	overload
P, p	pulse
Q, q	turn-off
R, r	as first subscript: reverse (or reverse transfer), rise. As second subscript: repetitive, recovery. As third subscript: with a specified resistance between the terminal not mentioned and the reference terminal
(RMS), (rms)	root-mean-square value

(1) For the purpose of this publication, the term 'electrical parameters' applies to four-pole matrix parameters, elements of electrical equivalent circuits, electrical impedances and admittances, inductances and capacitances.

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S, s	as first subscript: series, source, storage, stray, switching. As second subscript: surge (non-repetitive). As third subscript: short circuit between the terminal not mentioned and the reference terminal
stg	storage
th	thermal
TO	threshold
tot	total
W	working
X, x	specified circuit
Z, z	reference or regulator (zener)
1	input (four-pole matrix)
2	output (four-pole matrix).

**Applications and examples****TRANSISTOR CURRENTS**

The first subscript indicates the terminal carrying the current (conventional current flow from the external circuit into the terminal is positive).

Examples:  $I_D$ ,  $i_D$ ,  $i_d$ ,  $I_{dm}$ .

**TRANSISTOR VOLTAGES**

A voltage is indicated by the first two subscripts: the first identifies the terminal at which the voltage is measured and the second the reference terminal or the circuit node. The second subscript may be omitted when there is no possibility of confusion.

Examples:  $V_{GS}$ ,  $v_{GS}$ ,  $v_{gs}$ ,  $V_{gsm}$ .

**SUPPLY VOLTAGES OR CURRENTS**

Supply voltages or supply currents are indicated by repeating the appropriate terminal subscript.

Examples:  $V_{DD}$ ,  $I_{SS}$ .

A reference terminal is indicated by a third subscript.

Example:  $V_{DDS}$ .

**DEVICES WITH MORE THAN ONE TERMINAL OF THE SAME KIND**

If a device has more than one terminal of the same kind, the subscript is formed by the appropriate letter for the terminal, followed by a number. Hyphens may be used to avoid confusion in multiple subscripts.

**Examples:**

$I_{G2}$	continuous (DC) current flowing into the second gate terminal
$V_{G2-S}$	continuous (DC) voltage between the terminals of second gate and source.

**MULTIPLE DEVICES**

For multiple unit devices, the subscripts are modified by a number preceding the letter subscript. Hyphens may be used to avoid confusion in multiple subscripts.

**Examples:**

$I_{2D}$	continuous (DC) current flowing into the drain terminal of the second unit
$V_{1D-2D}$	continuous (DC) voltage between the drain terminals of the first and second units.

**ELECTRICAL PARAMETERS**

The upper-case variant of a subscript is used for the designation of static (DC) values.

**Examples:**

$g_{FS}$	static value of forward transconductance in common-source configuration (DC current gain)
$R_{DS}$	DC value of the drain-source resistance.

The static value is the slope of the line from the origin to the operating point on the appropriate characteristic curve, i.e. the quotient of the appropriate electrical quantities at the operating point.

The lower-case variant of a subscript is used for the designation of small-signal values.

**Examples:**

$g_{fs}$	small-signal value of the short-circuit forward transconductance in common-source configuration
$Z_i = R_i + jX_i$	small-signal value of the input impedance.

If more than one subscript is used, subscripts for which a choice of style is allowed, the subscripts chosen are all upper-case or all lower-case.

Examples:  $h_{FE}$ ,  $y_{RE}$ ,  $h_{fe}$ ,  $g_{FS}$ .

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### FOUR-POLE MATRIX PARAMETERS

The first letter subscript (or double numeric subscript) indicates input, output, forward transfer or reverse transfer.

Examples:  $h_i$  (or  $h_{11}$ ),  $h_o$  (or  $h_{22}$ ),  $h_f$  (or  $h_{21}$ ),  $h_r$  (or  $h_{12}$ ).

A further subscript is used for the identification of the circuit configuration. When no confusion is possible, this further subscript may be omitted.

Examples:  $h_{fe}$  (or  $h_{21e}$ ),  $h_{FE}$  (or  $h_{21E}$ ).

### DISTINCTION BETWEEN REAL AND IMAGINARY PARTS

If it is necessary to distinguish between real and imaginary parts of electrical parameters, no additional subscripts are used. If basic symbols for the real and imaginary parts exist, these may be used.

Examples:  $Z_i = R_i + jX_i$ ,  $y_{fe} = g_{fe} + jb_{fe}$ .

If such symbols do not exist or are not suitable, the notation shown in the following examples is used.

Examples:

$\text{Re}(h_{ib})$  etc. for the real part of  $h_{ib}$ .

$\text{Im}(h_{ib})$  etc. for the imaginary part of  $h_{ib}$ .

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